

Feature Mapping: post-processing gridded products to refine ocean features

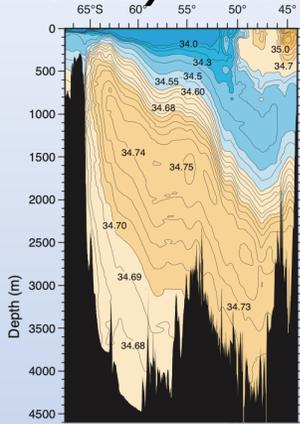
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Hydrographic sections fit data closely ... but models don't

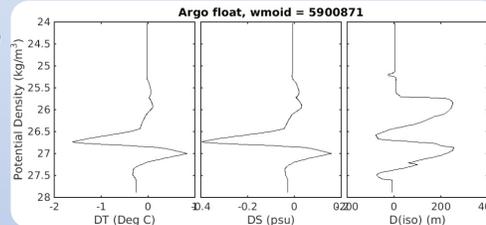
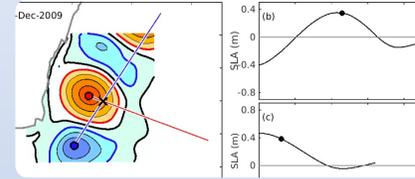
→ Hydrographic sections often show small-scale, small-amplitude features that are important.
→ Models generally show smooth fields, lacking many details, even in reanalyses.

Figure 1: This example, along WOCE line S3 (P12) is sufficient to resolve features with local maxima of 0.01 psu at 1650 m depth and 55°S.

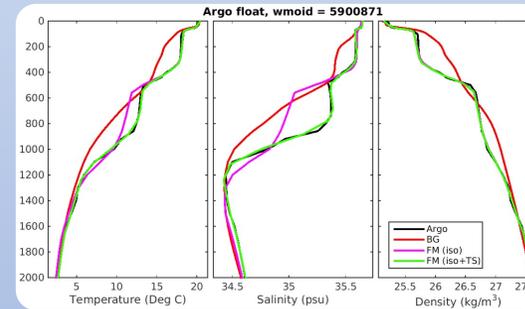


What is Feature Mapping?
Post-processing of gridded products to adjust TS-properties and isopycnal depths ... to better “fit” observations.

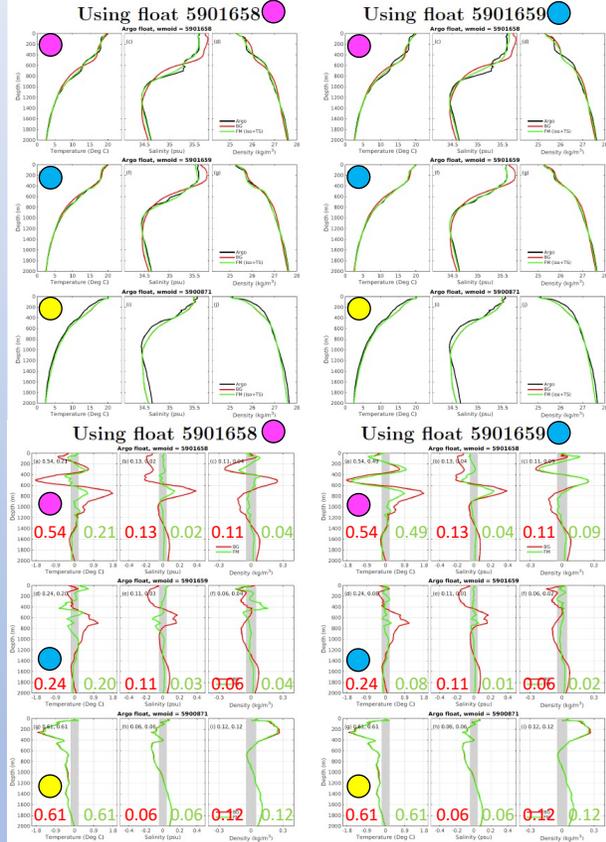
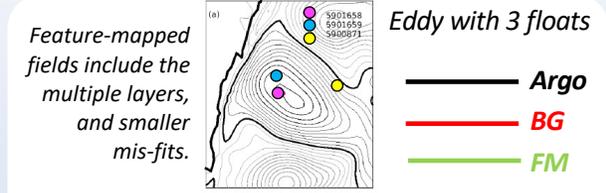
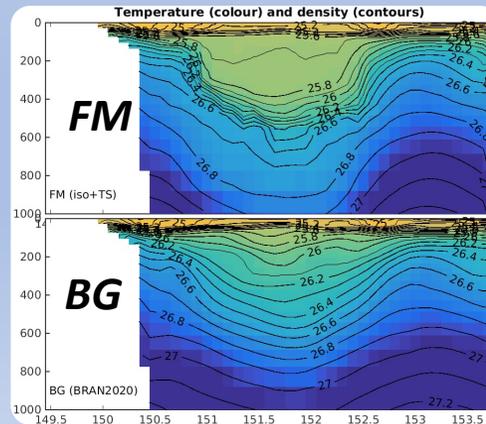
Step 1: Identify the target feature and Argo profiles within the feature.



Step 2: Calculate the differences of temperature, salinity, and isopycnal depths in density space.
... construct a look-up table.



Step 3 & 4: Adjust the TS-properties and then isopycnal depths using the look-up table for the entire feature.
Step 5: Apply convective adjustment.



Concept

- Models tend to under-exploit observations, often missing key features.
- Argo buddies suggest gridded fields should fit to within ~0.1°C, ~0.04 psu, isopycnal depths to within ~10 m
- Feature mapping borrows ideas from weather forecasting (post-processing) to refine gridded fields.
- Profiles can be made to fit precisely.

Next Steps

- Use multiple profiles in a single step
- Produce regional and possibly global feature-mapped fields
- Assess using experiments with known “true” fields.

How closely should models “fit” observations?

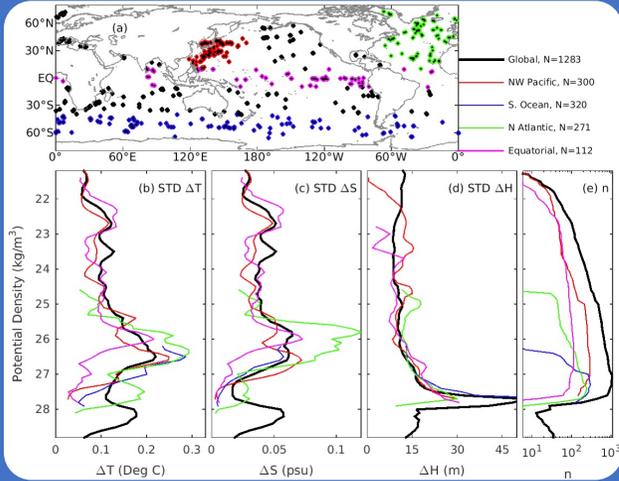


Figure 2: Argo “buddy” floats within 10 km & 12 hours, showing differences for 0.1°C, 0.04 psu, and 10 m depth (for isopycnal depths). [Colours denote regions; excludes top 50 m]